Highlights of the EXCLAIM collaboration

Simonetta Liuti

"The EIC will be a particle accelerator that collides electrons with protons and nuclei to produce snapshots of those particles' internal structure—like a CT scanner for atoms. The electron beam will reveal the arrangement of the quarks and gluons that make up the protons and neutrons of nuclei."

https://www.bnl.gov/eic/

One prominent example of the importance of imaging: the Event Horizon Telescope (EHT) imaged an object as far as 55 M light-years = 5×10^{23} m

> \triangleright But what is the science that goes into imaging the proton, observing its spatial structure at 10⁻¹⁵ m?

SgsA* (

 $OOCC$

M87* (first image, no ML, 2017)

The EXCLAIM collaboration

https://willuhmjs.github.io/exclaim/

PIs: Marie Boer, Gia-Wei Chern , Michael Engelhardt, Gary Goldstein, Yaohang Li, Huey-Wen Lin, SL, Matt Sievert, (Dennis Sivers)

Funded Postdocs: Douglas Adams, Marija Cuic, Liam Hockley, Saraswati Pandey, Emanuel Ortiz, Kemal Tezgin

Graduate Students: Andrew Dotson, Carter Gustin, Jang (Jason) Ho, Fayaz Hossen, Adil Khawaja, Zaki Panjsheeri, Anusha Singireddy, Jitao Xu

Undergraduate: Will Faircloth

EXCLAIM Collaboration Budget by Institution

Scope of project/Deliverables timeline

Standard Approach to ML/AI in Physics

Standard Approaches: Industrial Machine Learning (ML) tools are used/adapted to aid computation in Nuclear/Particle Physics

Example: Ensemble learning methods such as Boosted Decision Trees (BDT) invented for image recognition/object detection used in self-driving cars are used to identify b-hadrons

https://atlas.cern/

To address the "why"?

• We introduce physics aware NNs as explainable ML models: C-VAIM

• Symbolic Regression: ML algorithm where data are modeled directly with analytic expressions. Direct interpretability

• Explainable/interpretable models are necessary for the 3D nuclear problem directly enabling discovery of laws in Nuclear and Particle Physics

• Not just a set of advanced computational tools: It is about finding a common language between physics and AI

Forward Problem

• **Interpretability + predictions**

The goal in physics is to extract information as accurately as possible from data/concise understandable equations/generalizable

• **Only Predictivity**

The goal of ML is to obtain statistical models that can make predictions from the data/no interpretability

An immense potential!

Through ML we will be able to uncover **new physics relations/laws**

• **Inverse problem**

ML emergent behavior is decades from being understood!

To extract model information from data we need to define a bridge between CS experts and physicists that is centered on how we define and treat the respective data uncertainty and correlations while being aware that their objective functions differ

Physics Case: Extracting information from exclusive deeply virtual scattering

QCD matrix element

Experiment

Generalized Parton Distributions

Moments → Energy Momentum Tensor Form factors

Angular momentum, Mass

Twist three GPD Physical interpretation at the core of spin puzzle

$$
\frac{J_L}{2} = \frac{L_L}{2\pi\sqrt{dx}} + \frac{S_L}{2\pi\sqrt{dx}} + \frac{1}{2} \int dx \,\widetilde{H}
$$
\n
$$
= \frac{\int dx \, F_{14}^{(1)}}{\int dx \, F_{14}^{(1)}} + \frac{1}{2} \int dx \,\widetilde{H}
$$

A. Rajan, M. Engelhardt and S. Liuti, Phys. Rev. D98, 074022 (2018) A. Rajan, A. Courtoy, M. Engelhardt and S. Liuti, Phys. Rev. D94, 034041 (2016) M. Rodekamp, M. Engelhardt, J.R. Green, S. Krieg, S. Liuti, S. Meinel, J.W. Negele, A. Pochinsky and S. Syritsyn, Phys. Rev. D 109, 074508 (2024)

*Twist 3 GPD notation from Meissner, Metz and Schlegel, JHEP(2009)

Transverse Angular Momentum Sum Rule

O. Alkassasbeh, M. Engelhardt, SL and A. Rajan, https://arxiv.org/abs/2410.21604

$$
\frac{1}{2}\int dx x (H+E) - \frac{1}{2}\int dx \mathcal{M}_T = \int dx x (\widetilde{E}_{2T} + H + \mathcal{E}_{\mathcal{F}}) + \frac{1}{2}\int dx g_T - \frac{1}{2}\int dx x \mathcal{A}_T
$$

$$
J_T
$$

Extract Compton Form Factors from Leading order parametrization of DVCS cross section

Azimuthal angle ϕ dependent coefficients

$$
|T_{UU}^{BH}|^2 = \frac{\Gamma}{t} \left[A_{UU}^{BH} \overline{K_1^2 + \tau F_2^2} + B_{UU}^{BH} \overline{K_1^2 \overline{K_2^2 \overline{K_1^2}}(t) \right]
$$

\n
$$
|T_{UU}^{TM}|^2 = \frac{\Gamma}{Q^2 t} \left[A_{UU}^T \Re\left(\overline{F_1 H} + \tau F_2 \overline{\mathcal{E}} \right) + B_{UU}^T G_M \Re\left(\overline{H} + \overline{\mathcal{E}} \right) + C_{UU}^T G_M \Re\widehat{H} \right]
$$

\n
$$
|T_{UU}^{TM}|^2 = \frac{\Gamma}{Q^2 t} \left[A_{LU}^T \Im\{ \overline{F_1 H} + \tau F_2 \overline{\mathcal{E}} \} \right] + B_{LU}^T G_M \Im\{ \overline{H} + \overline{\mathcal{E}} \} + C_{LU}^T \overline{G_M} \Im\{ \overline{H} \}
$$

\n
$$
|T_{UU}^{DVCS}|^2 = \frac{\Gamma}{Q^2} \frac{2}{1 - \epsilon} \left[(1 - \xi^2) \left[(\Re\epsilon H)^2 + (\Im\{ H} + \overline{\mathcal{E}} \mathcal{E})^2 + (\Re\epsilon H)^2 + (\Im\{ H} + \overline{\mathcal{E}} \mathcal{E})^2 \right] \right]
$$

\n
$$
+ \frac{t_o - t}{4M^2} \left[(\Re\epsilon \epsilon)^2 + (\Im\{ H} + \overline{\mathcal{E}} \mathcal{E})^2 + \overline{\mathcal{E}}^2 (\Re\epsilon \overline{\mathcal{E}})^2 + \xi^2 (\Im\{ \overline{H} \mathcal{E} \mathcal{E})^2 \} \right]
$$

\n
$$
- 2\xi^2 \left(\Re\{ H \Re\{ H} + \Re\{ H \Re\{ H} \mathcal{E} \mathcal{E} + \Im\{ H \}\} \Re\{ \overline{\mathcal{E}} \} \right)
$$

- B. Kriesten et al, *Phys.Rev. D* 101 (2020)
- B. Kriesten and S. Liuti, *Phys.Rev. D105 (2022),* arXiv [2004.08890](https://arxiv.org/abs/2004.08890)
- B. Kriesten and S. Liuti, Phys. Lett. B829 (2022), arXiv:2011.04484

First Inverse Problem!

 $(QCDKernel) \times GPD$ **CFF**

Assume known

3D Coordinate Space Representation requires a Fourier transform

Observables from DVES matrix elements can be Fourier transformed from momentum space into coordinate space, providing insight into the spatial distributions of quarks and gluons inside the proton, besides matter and charge distributions.

EXCLAIM Research Accomplishments

- 1. Fully constraining Likelihood analysis
- 2. Inverse Problem techniques: Variational Autoencoder Inverse Mapper (VAIM)
- 3. Symbolic Regression for Partonic Observables

All these methods share the common goal of going beyond simple regression by understanding the underlying correlations of the system

1. Fully Constraining CFFs : Likelihood Analysis

Graduate Students: Joshua Bautista, Adil Khawaja, Zaki Panjsheeri

GOAL: Use DVCS data and comparing to cross section model to find CFFs

- Curve fit: A bad result: Encounter a problem 1!
- Definition of the likelihood: Try to fix the problem
- Canonical Likelihood: Reproduces the problem in explainable way
	- Difference method Likelihood
	- Canonical Likelihood
- Encounter a problem 2 : covariance
- Results: Table of CFFs and errors

Degeneracy of Curve Fit Results

Covariance of CFF Results

- Here the maximum likelihood is achieved allowing 3 CFFs to vary.
- Only 23 combinations of 2 angles are used.

Marginal Posterior CFF Results

26

2. Inverse Problem Techniques: VAIM, C-VAIM, MCMC

Approaches to find parameters statistically in an underdetermined system:

- Can quantify parameter uncertainty when more parameters than data
- Techniques highly dependent on bounded parameter priors
- These methods give us an initial way to perceive:
	- o the correlation between parameters on a complicated model
	- what information is missing (latent space)

arXiv: [2405.05826](https://arxiv.org/abs/2405.05826) **A variational autoencoder inverse mapper solution to Compton form factor extraction from deeply virtual exclusive reaction**

• KMNN, <https://arxiv.org/abs/2007.00029>

CFFs Analysis of Latent Space

3. Symbolic Regression for Parton Research

- 1) What is symbolic regression and why do we care?
	- a) Spoiler: because then humans can read the answer
- 2) What are the existing tools out there?
	- a) Eureka
	- b) Gplearn
	- c) AI Feynman
	- d) PySr
	- e) RL-SR
	- f) *Meijer-G-Function (very preliminary)

Graduate Students: Andrew Dotson (NMSU) Anusha SingiReddy (ODU) Zaki Panjsheeri (UVA)

What is symbolic regression (SR)?

Why bother with SR when we have neural networks?

vs

Which is easier to read? (a.k.a interpretability of AI)

$$
y=X_0^2-3\times X_1+0.5
$$

Testing x and t factorization (important for spatial configurations!)

Novel SR Convergence Clustering

Why is it important to check x and t factorization?

Consequences on the 3D Coordinate Space picture

GPDs can be Fourier transformed from momentum space into coordinate space, providing insight into the spatial distributions of quarks and gluons inside the proton, besides matter and charge distributions.

Slice of Wigner phase space distribution

$$
\mathcal{H}^{q}(X,0,b_{T}) = \int \frac{d^{2} \Delta_{T}}{(2\pi)^{2}} H^{q}(X,0,\Delta_{T}) e^{-i\Delta_{T} \cdot b_{T}}
$$

With Z. Panjsheeri and J. Bautista GPD

Gluon and quark matter density radius

$$
\langle b_T^2 \rangle^q(X) = \frac{\int_0^\infty d^2b_T b_T^2 \mathcal{H}^q(X,0,b_T)}{\int_0^\infty d^2b_T \mathcal{H}^q(X,0,b_T)}
$$

Bautista, Panjsheeri, SL (2024)

Compare to lattice and b^2 AdS/CFT integrated value K. Mamo and I. Zaeed PRD106, 086004 (2022) LQCD: Detmold and Shanahan

[arXiv:2405.05842](https://arxiv.org/abs/2405.05842)

From SR Analysis

Conclusions

- 1. A successful reconstruction of the **spatial structure of the proton** (and all of its mechanical properties) relies on our ability to understand the **cross section** for **all the various DVES processes**
- 2. This implies solving **multiple inverse problems**
- 3. We have defined a path to extract the **observables** from experiment that allows us to fully take into account UQ from data and ab initio QCD calculations
- 4. Bringing interpretability and benchmarking to AI tools is a necessity for us to progress faster towards understanding the 3D picture of the proton
- 5. Obtaining spatial images of the proton including UQ is feasible using AI/ML to extend the momentum transfer reach for an accurate Fourier transformation

Back up

Generalized Parton Distributions from Symbolic Regression

We have a lattice simulation of a GPD as a function of x, t, Q^2 The goal is to find a closed form expression for that GPD

Using a pareto front to choose amongst forms

Pareto front Illustration

PySR convergence

Andrew Dotson