

A Browser Based Toolkit for Improved Accelerator Controls

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RadiaSoft in a nutshell

- Incorporated in 2013 as a Delaware LLC
 - Growing organically via contract R&D
 - 24 employees in the US
 - Headquarters in Boulder, Colorado
- Software Expertise
 - UI design & development
 - Software security & sustainability
 - Cloud computing
 - Integrated simulation environments
 - Control system interfaces – collaborative between software & engineering
- Science and Engineering
 - Modeling, design, and optimization of physical systems
 - Radiation transport simulations and shielding
 - Machine learning
 - Control system development and LLRF

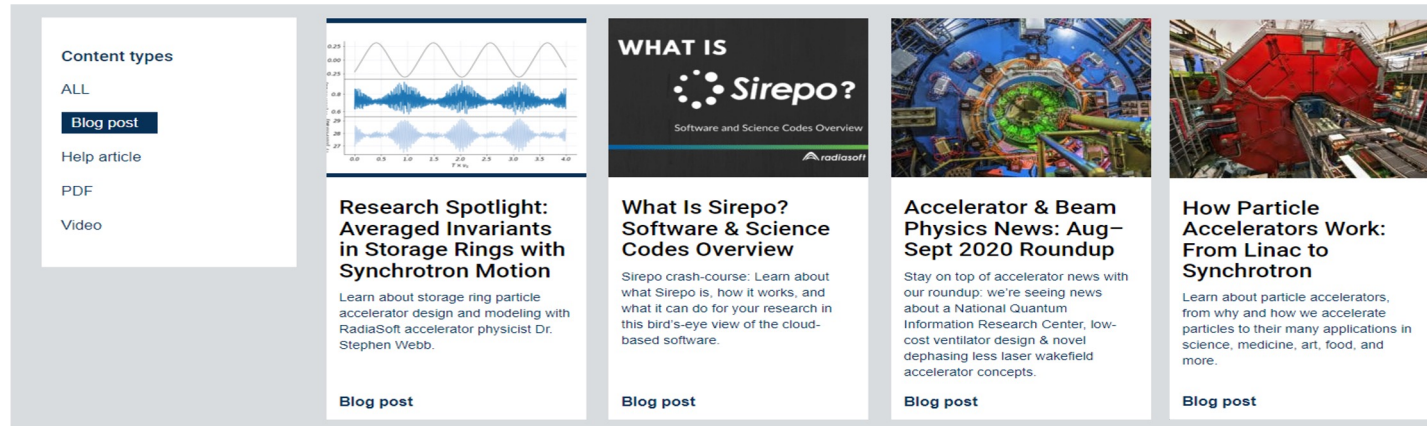
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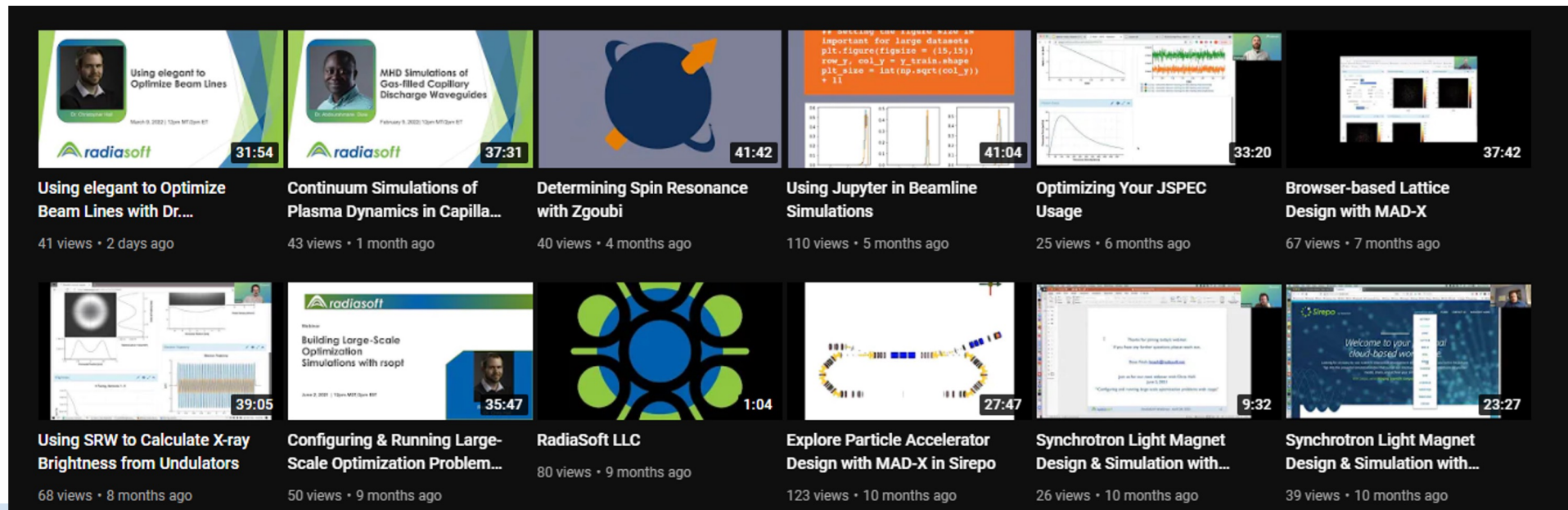


Community Outreach & Support

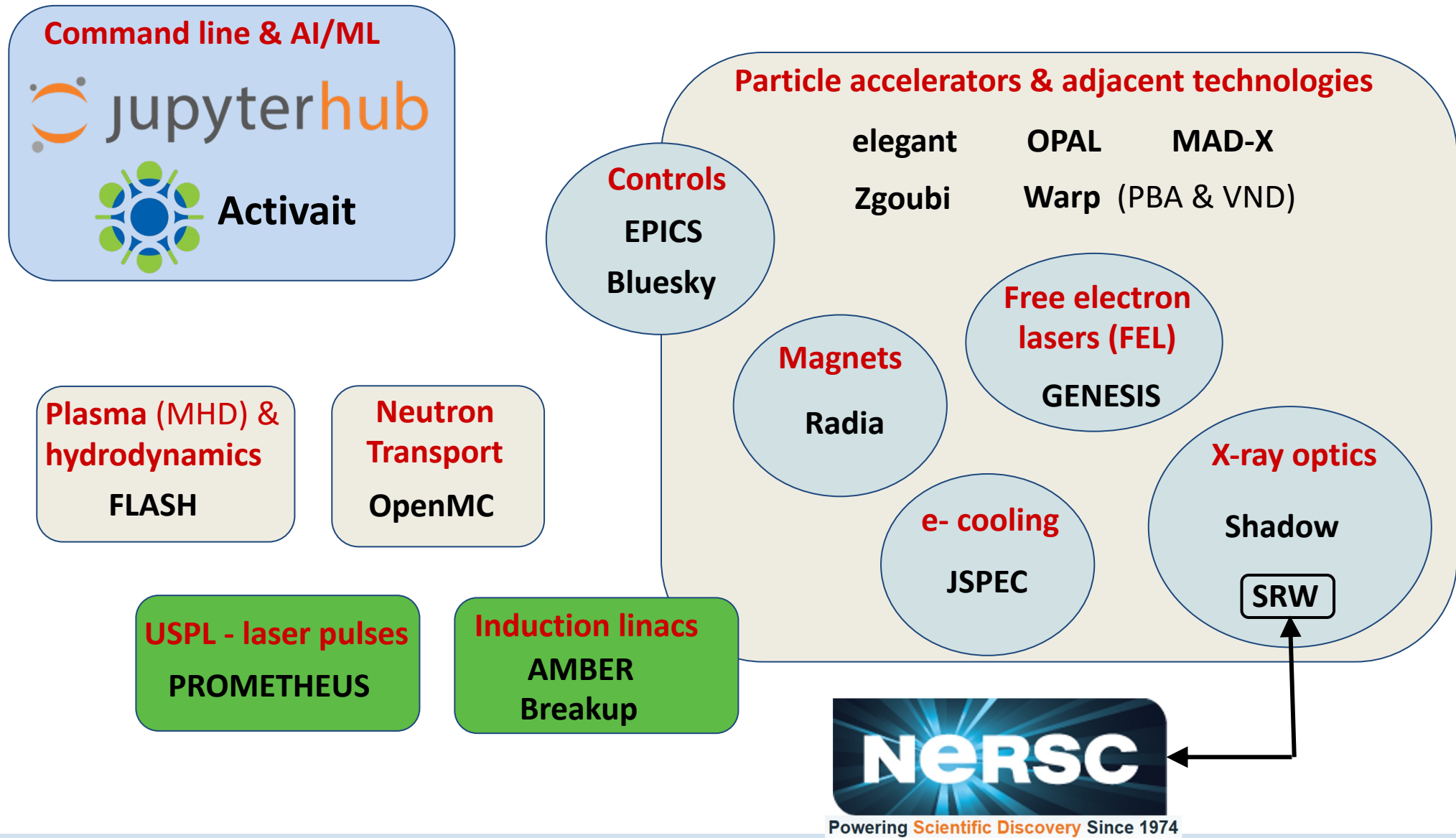


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Our monthly webinar series is available on YouTube, <https://www.youtube.com/c/RadiaSoft>

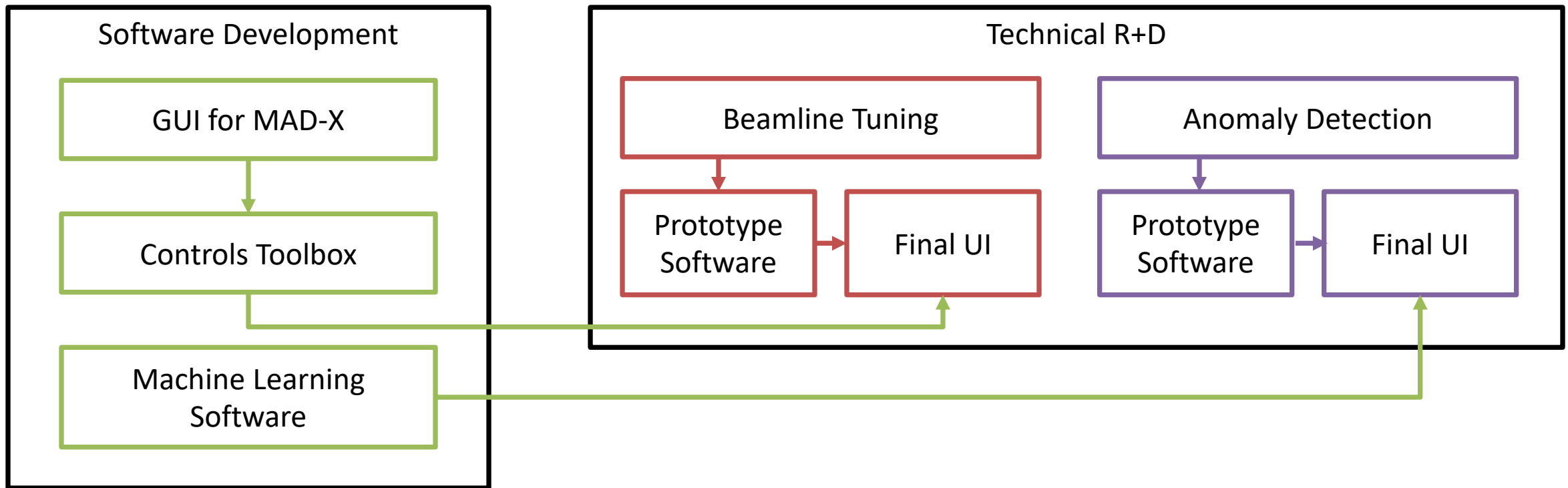


Sirepo supported codes and apps



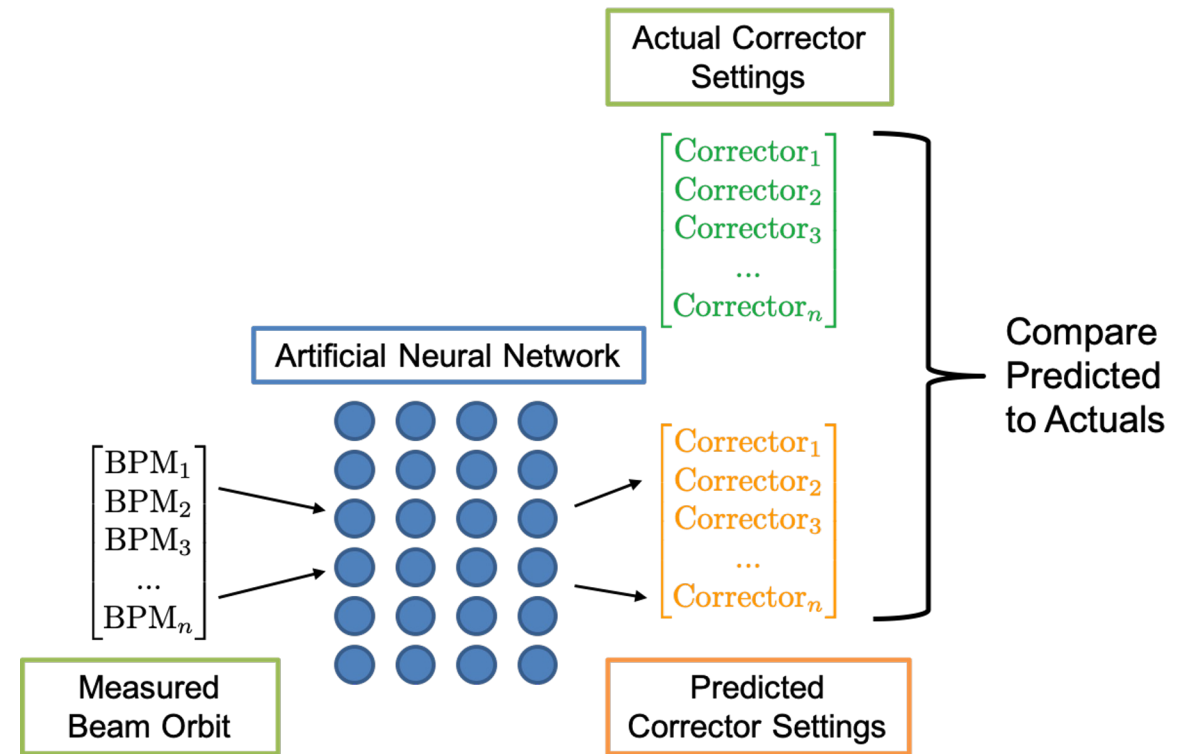
Project objectives

- 1) Demonstrate the deployment of custom control interfaces using our web-based toolbox
- 2) Test rapid reconfiguration of the BNL ATR Line between 5 and 10 GeV/u
- 3) Test a machine-learning based smart-alarm system at the CEBAF polarized electron source



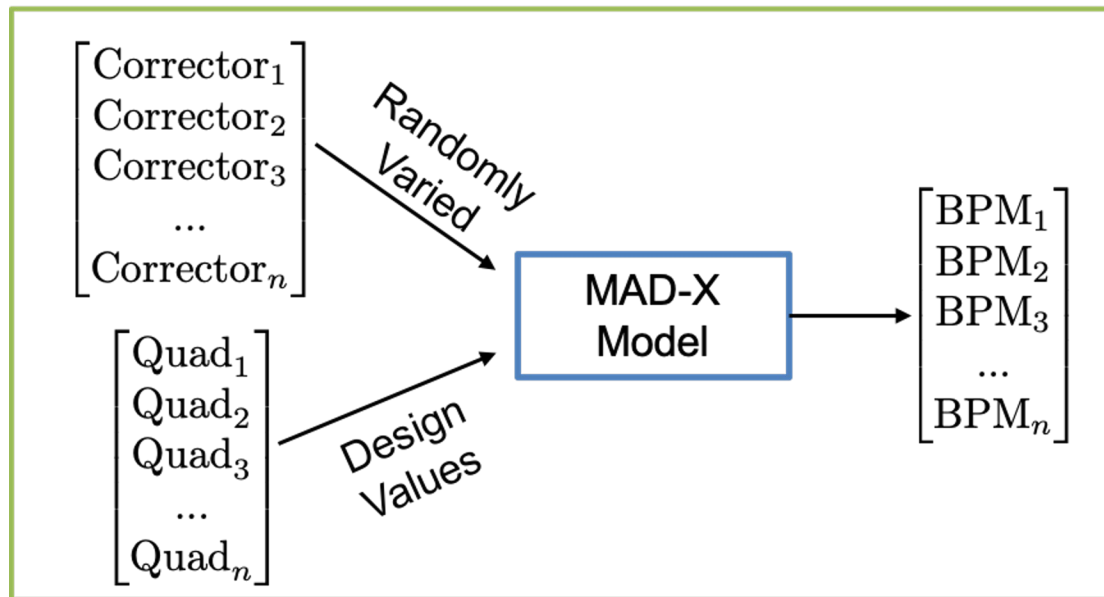
Inverse models for diagnostics and control at BNL

- Inverse models as a diagnostic in a supervised fashion
 - Direct comparison between predicted settings and actual settings informs operations of a potential anomaly with that magnet
- Inverse models as a diagnostic in an unsupervised fashion
 - Assumptions
 - model errors are caused by other beamline elements
 - each beam-line element will have a unique error signature
- Inverse models for tuning
 - Minimize error between predicted settings and actual settings by varying quads
 - Right: model error as a function of quad strength error

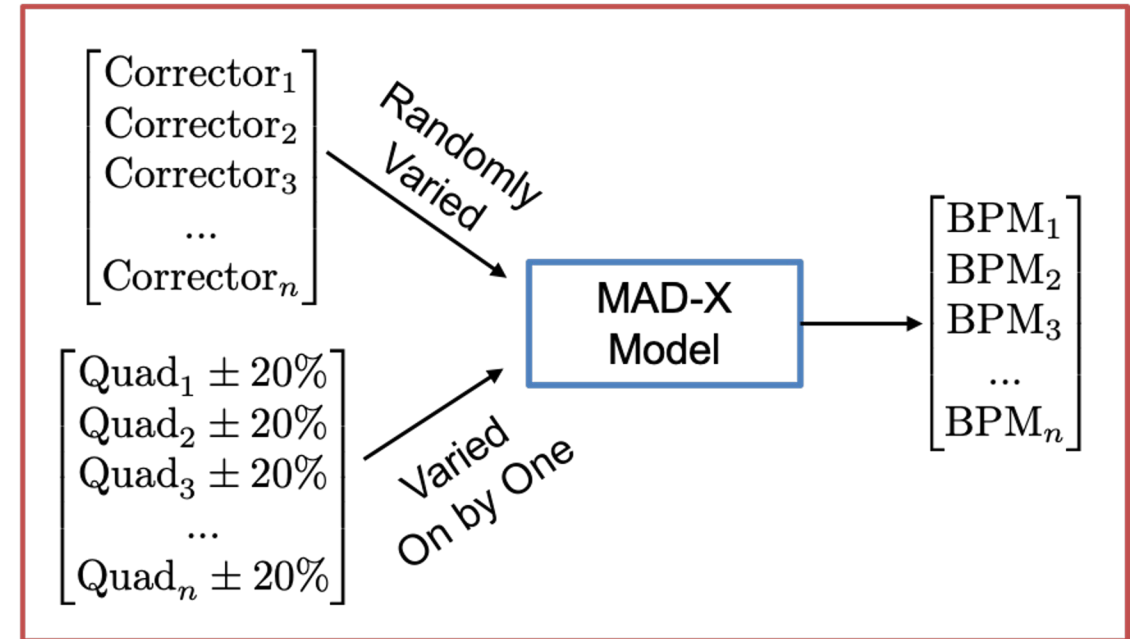


Data generation principles

Training Data Generation

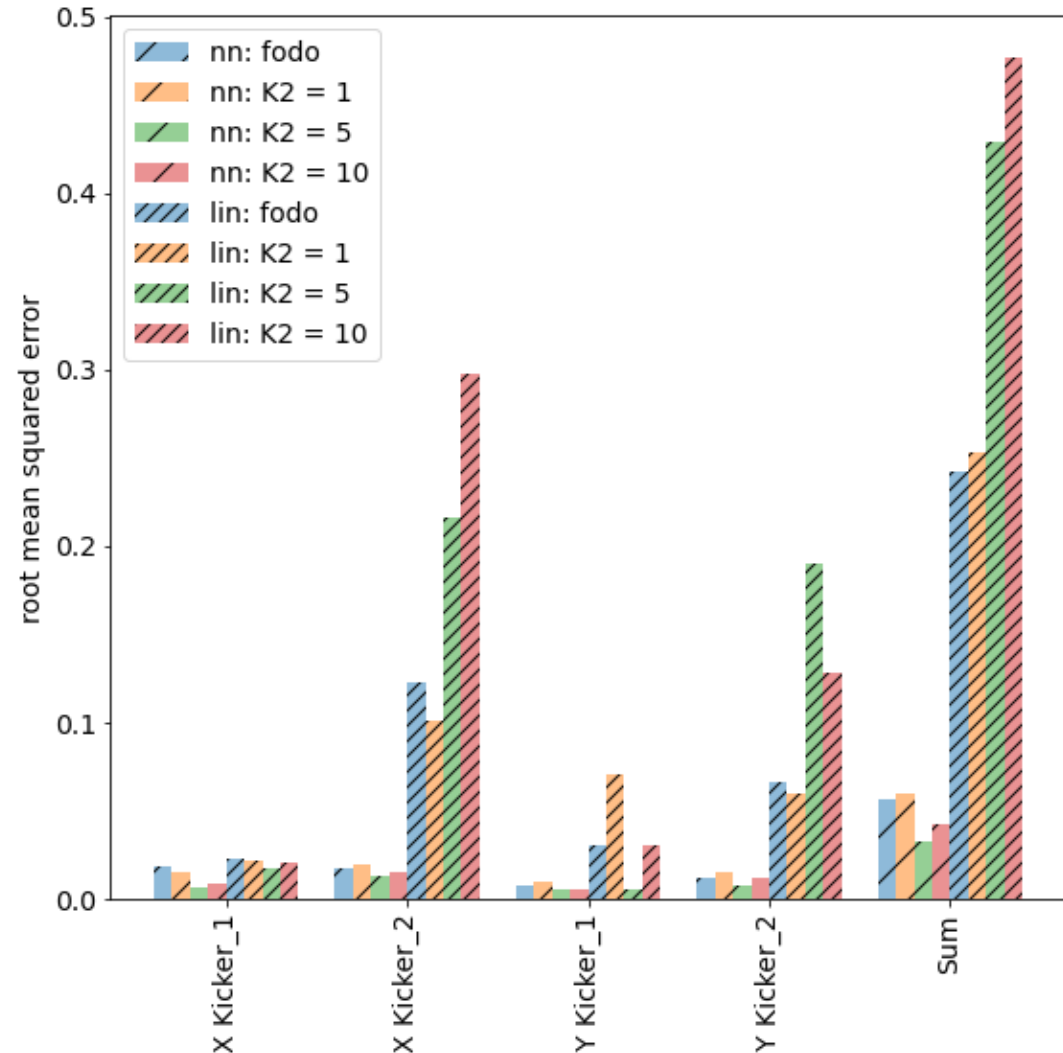
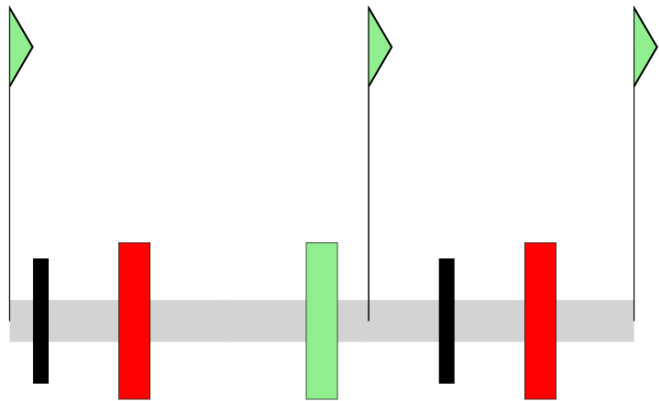


Test Data Generation



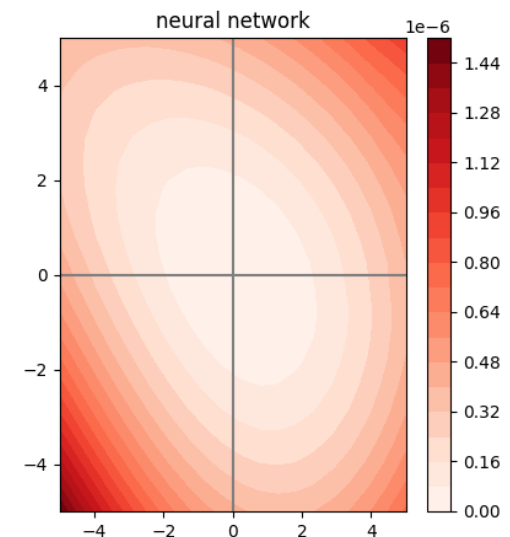
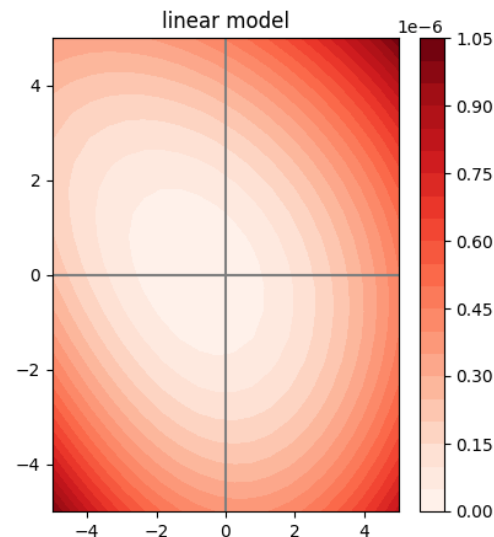
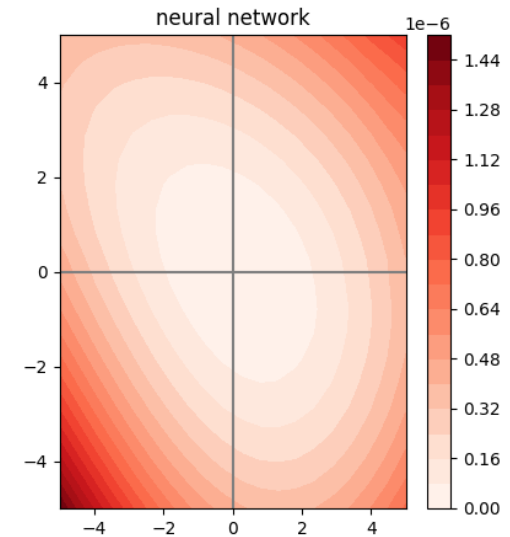
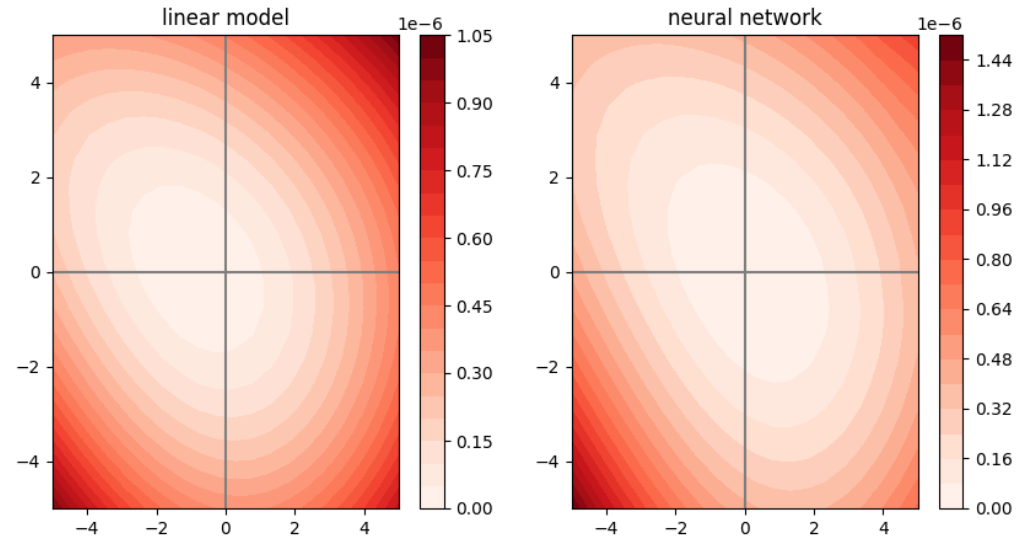
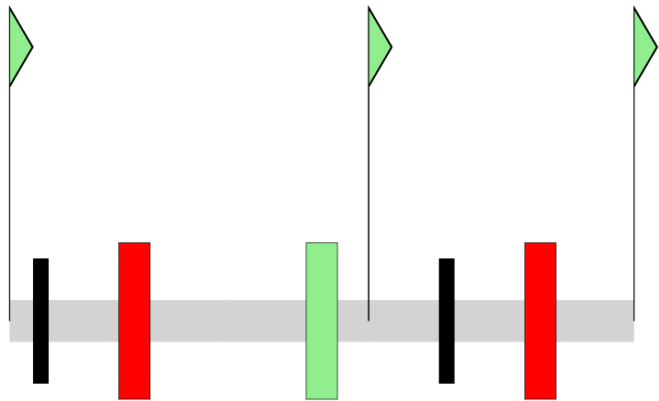
FODO cell example

- Train model using data with and without sextuple contributions
 - Different sextuple strengths
 - Examine both linear and neural network models
 - Neural network outperforms the liner model in all cases.



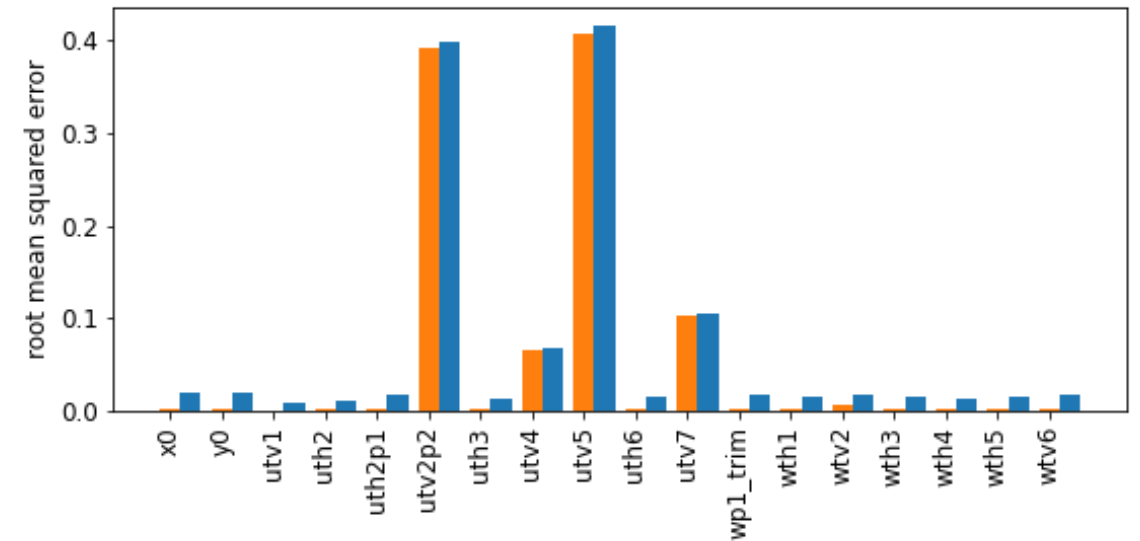
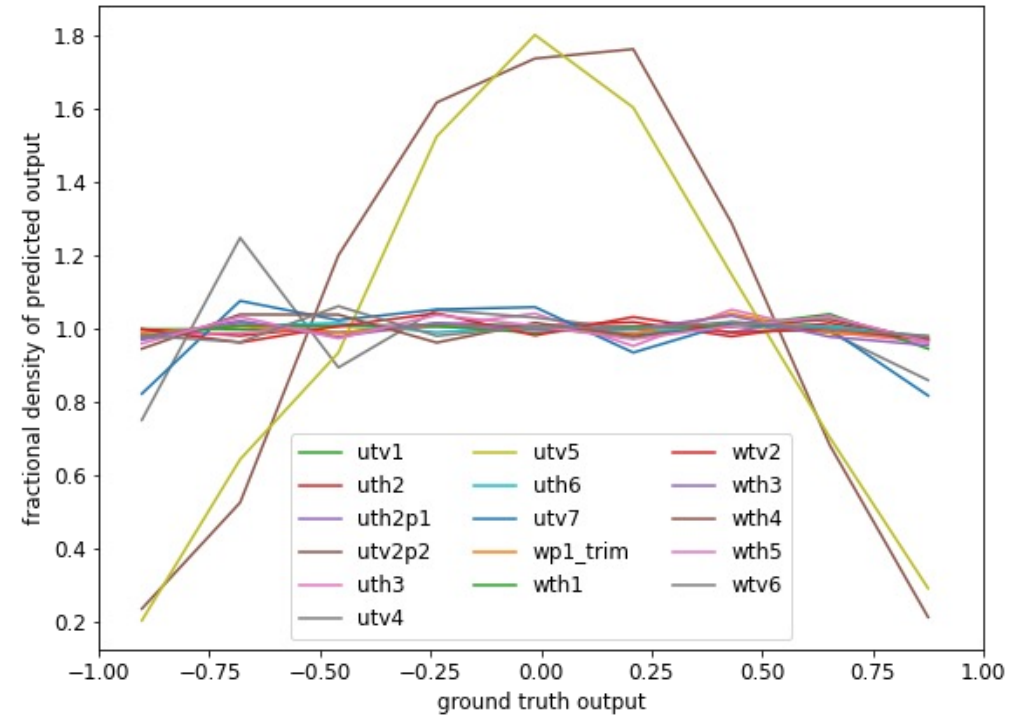
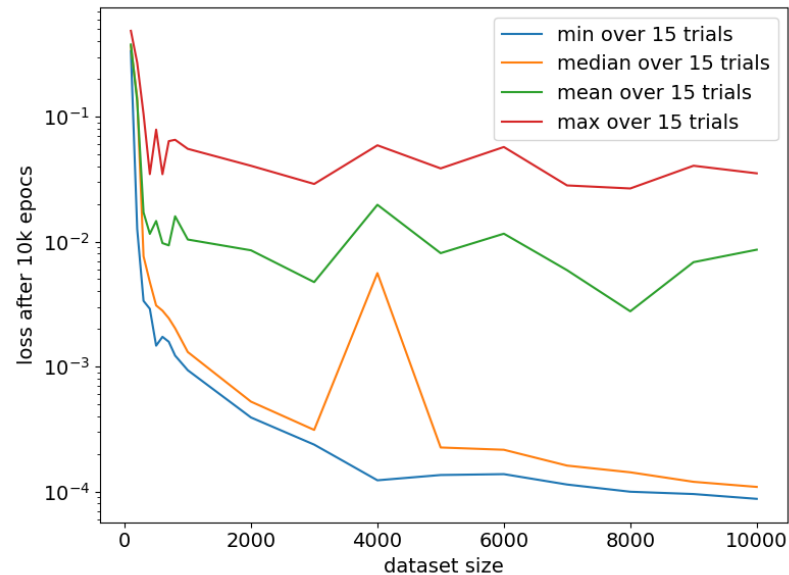
FODO cell example

- Evaluate model error as a function of quadruple strength
 - Compare linear and nonlinear models (left and right)
 - Compare with and without sextuple contributions (top and bottom)



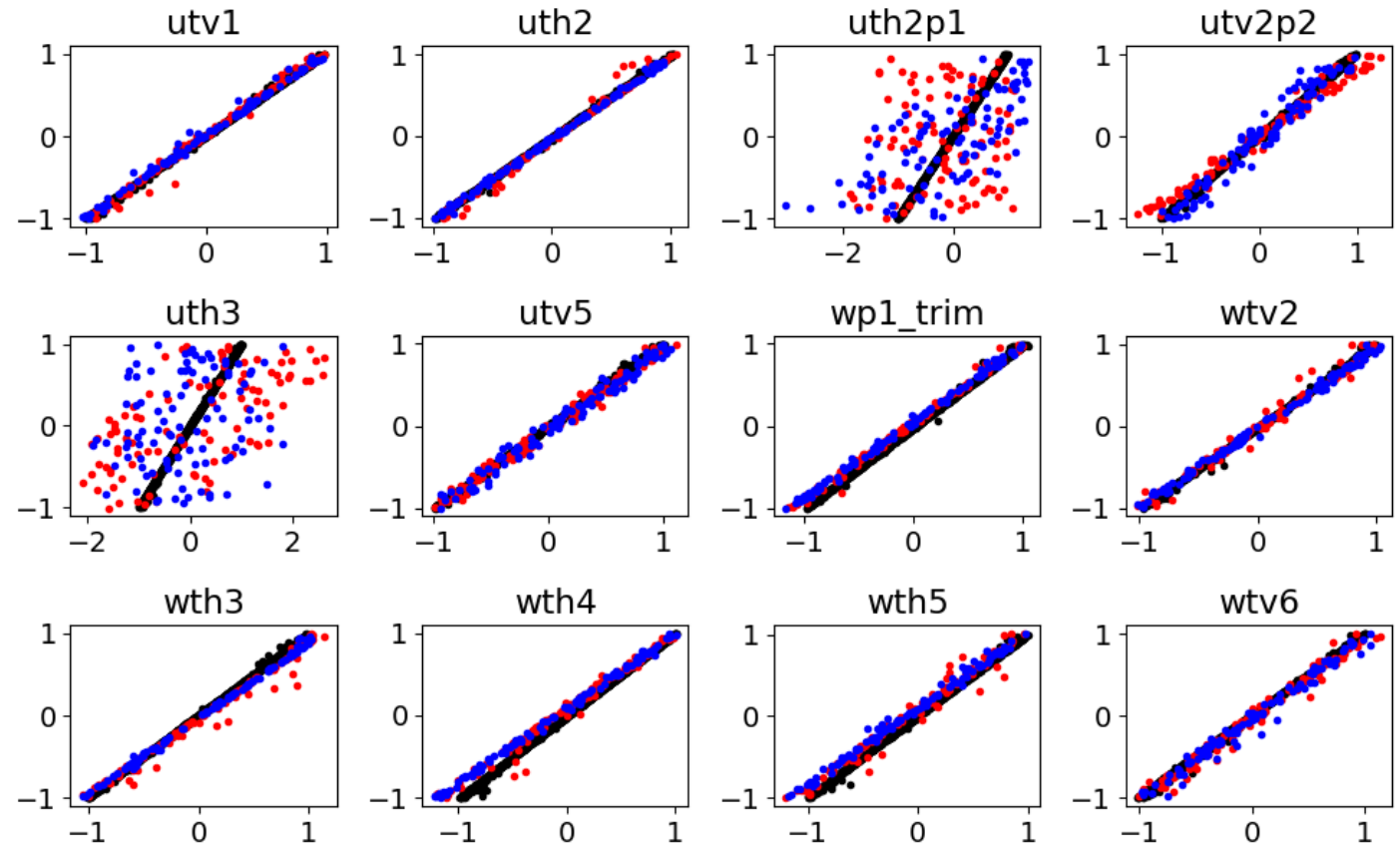
AGS to RHIC transfer line study

- Model training for the AGS to RHIC transfer line
 - Top Right: Fractional density of model error as a function of ground truth for each magnet
 - Bottom Right: RMS error as a function of magnet type
 - Bottom: model loss as a function of the dataset size



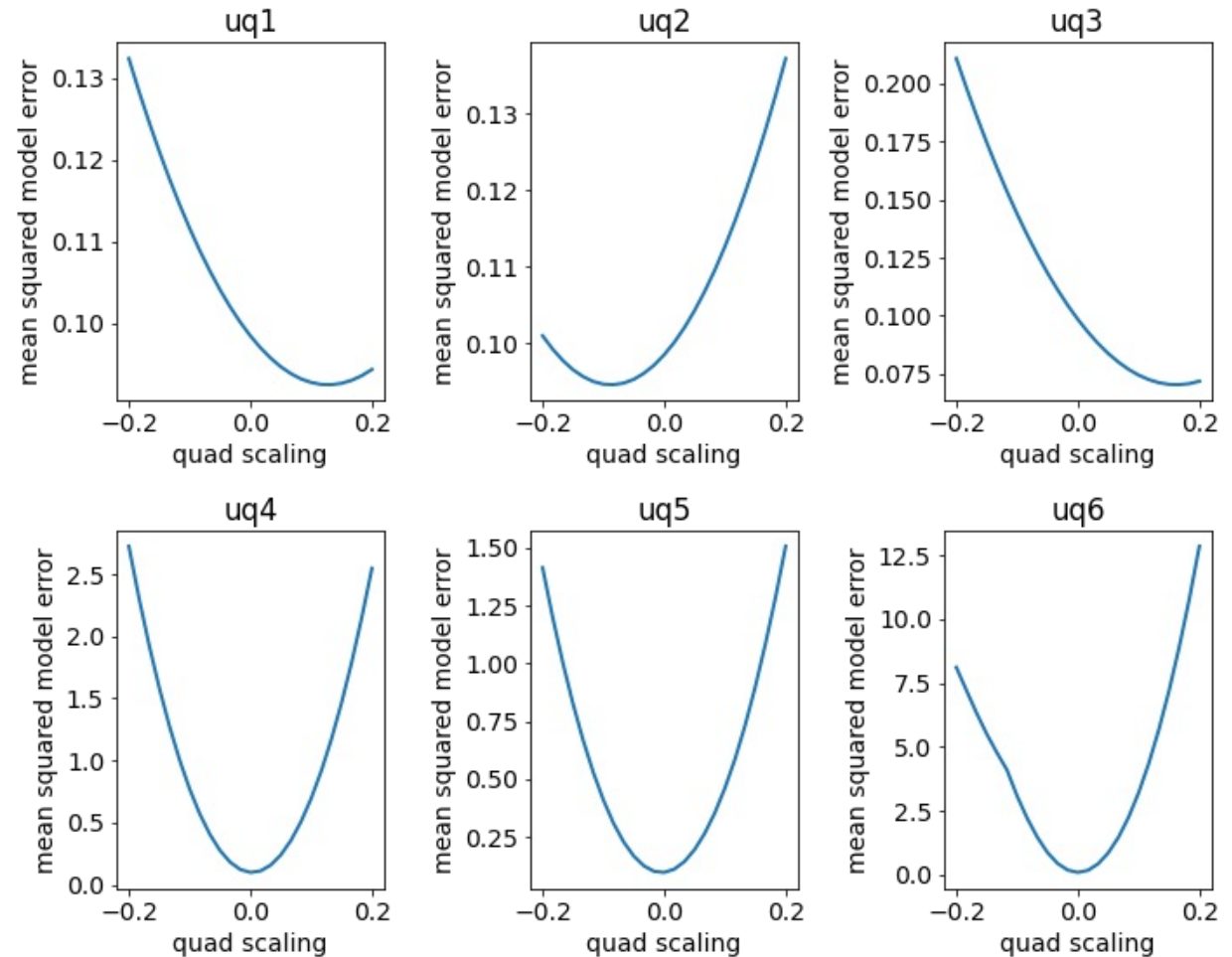
AGS to RHIC transfer line study

- Right: Predicted corrector settings vs the ground truth for the validation set
 - Black: without quadrupole errors
 - Red: a single quadrupole error of -20%
 - Blue: a single quadrupole error of +20%



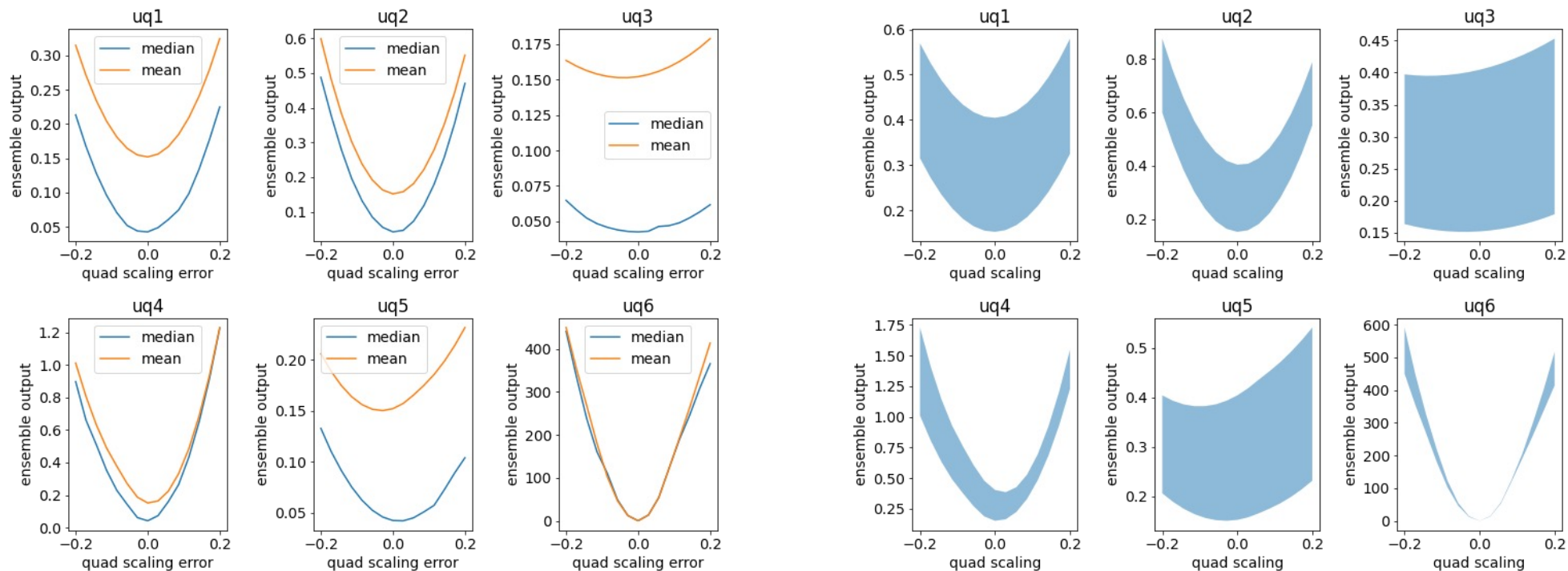
Computing the Model Loss as Quadrupoles are Varied

- Model trained for 100k epochs
- Individually varied the quads over a range of plus or minus 20% excitation
- All quads show sensitivity except uq6
- Many quads have minima at 0.0 with some offset
 - Longer training time can improve this
 - Ensemble methods may be more efficient



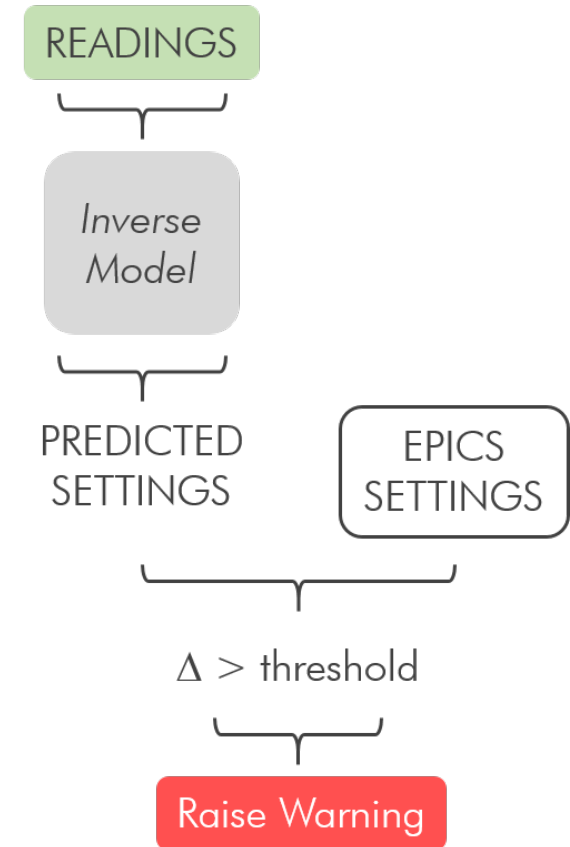
Consider an Ensemble of Models

- 23 models with random initializations: consider median and mean for output of the ensemble
- Examine the ensemble output as you vary the quad strengths
- Left: Ensemble output as a function of quad strength variation / Right: Ensemble output with ensemble variance
 - Note clearly defined minima at or very close to 1.0 for all cases except uq6
 - This is an improvement over slide 16 where some quads do not have well defined minima



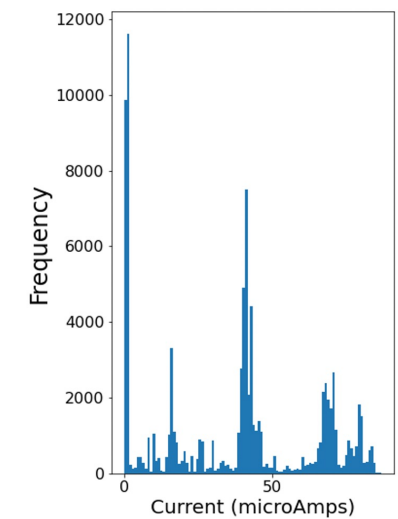
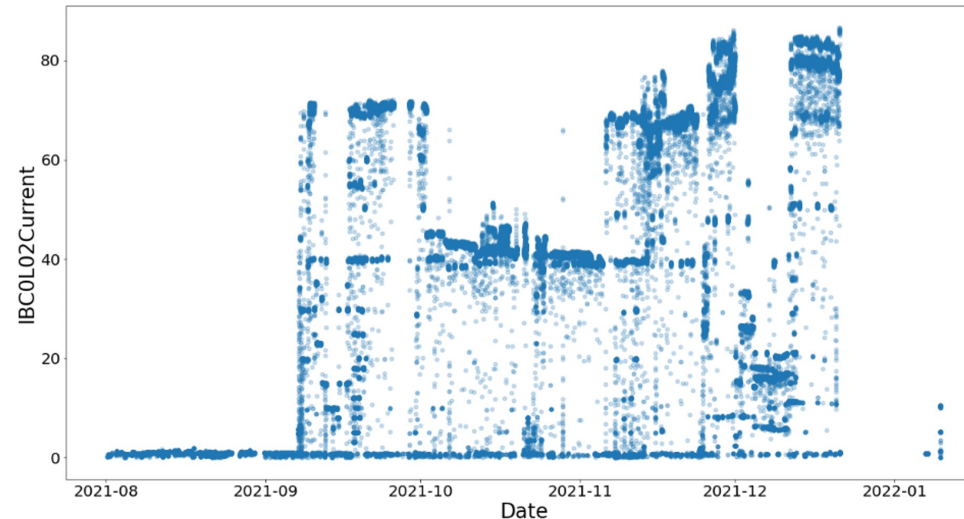
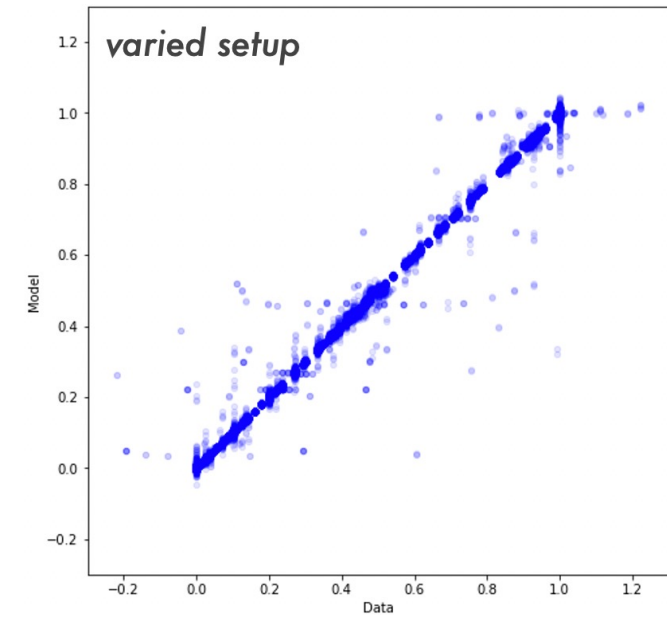
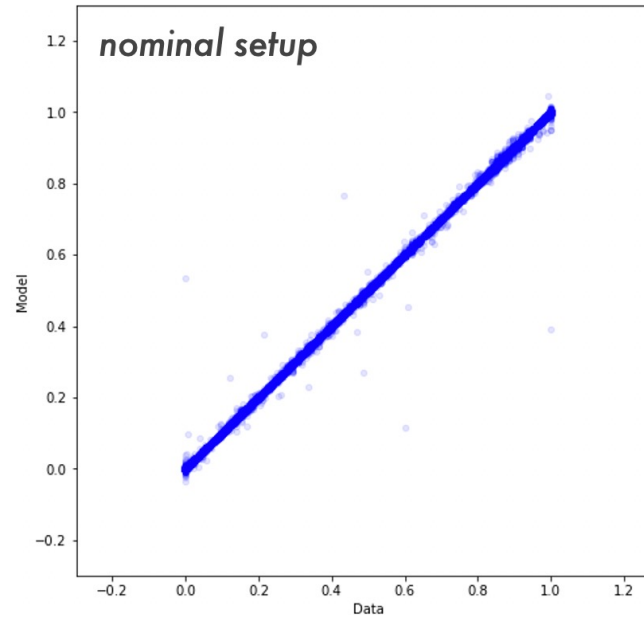
A Smart Alarm System for the CEBAF Injector

- Alarm systems typically alert operators when there is a problem with the beam
 - Often does not provide much information on what caused the alarm
 - Diagnosing the problems is time consuming for operators
- Use machine learning to automate the root-cause-analysis effort
 - Autoencoders quantify similarities or differences between machine states
 - Inverse models use actual measurements to predict settings



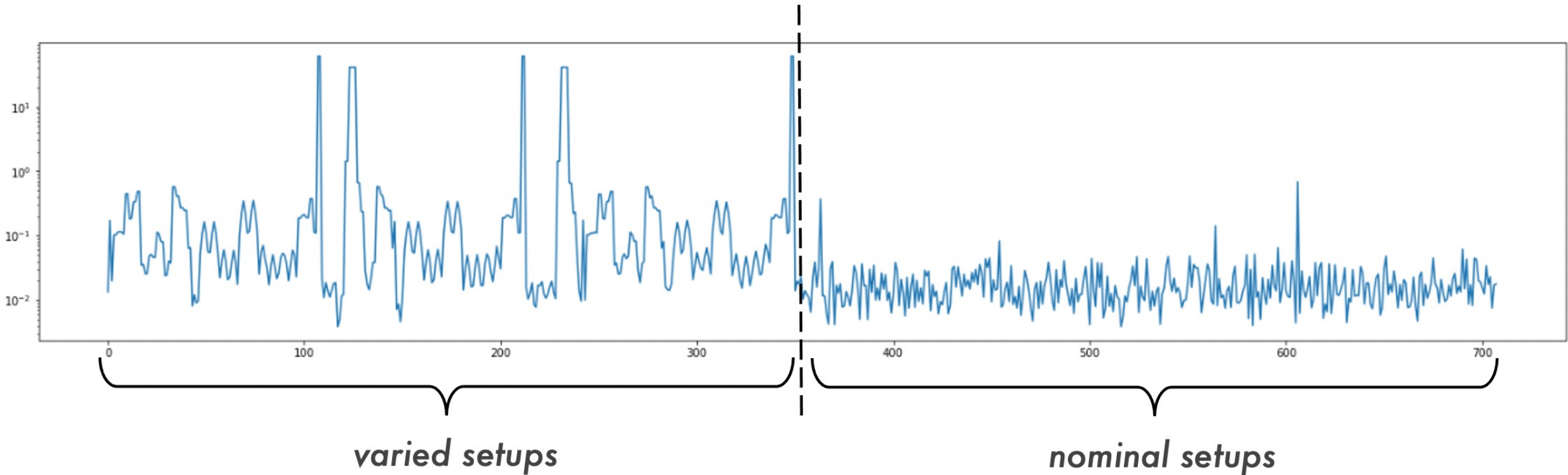
A Smart Alarm System for the CEBAF Injector

- Data collected during two different operational modes.
 - First during normal operations
 - Second during a dedicated machine study where parameters were varied
- Neural network inverse model is trained to predict settings from readings
 - Left: Model prediction vs the ground truth for the validation data from the nominal setup
 - Right: Model prediction vs the ground truth for the test data (study data)



A Smart Alarm System for the CEBAF Injector

- RMS error of the predicted settings by parameter for the machine study (left) and the nominal setup (right).
- The difference is indicative of the model being able to detect variations in the machine state.

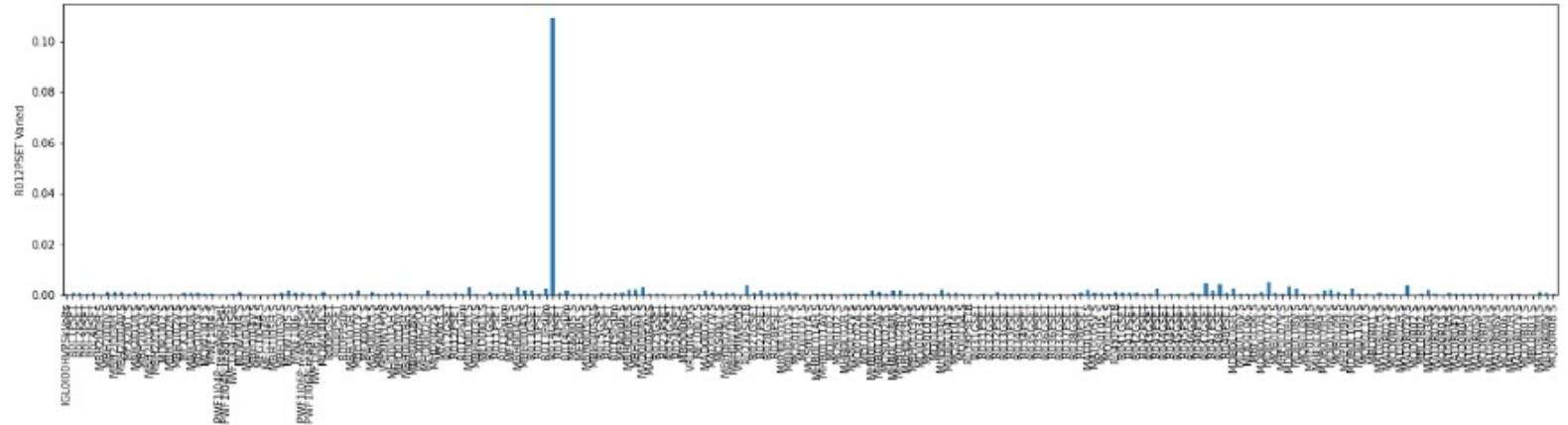


A Smart Alarm System for the CEBAF Injector

R014GSET → 28.28

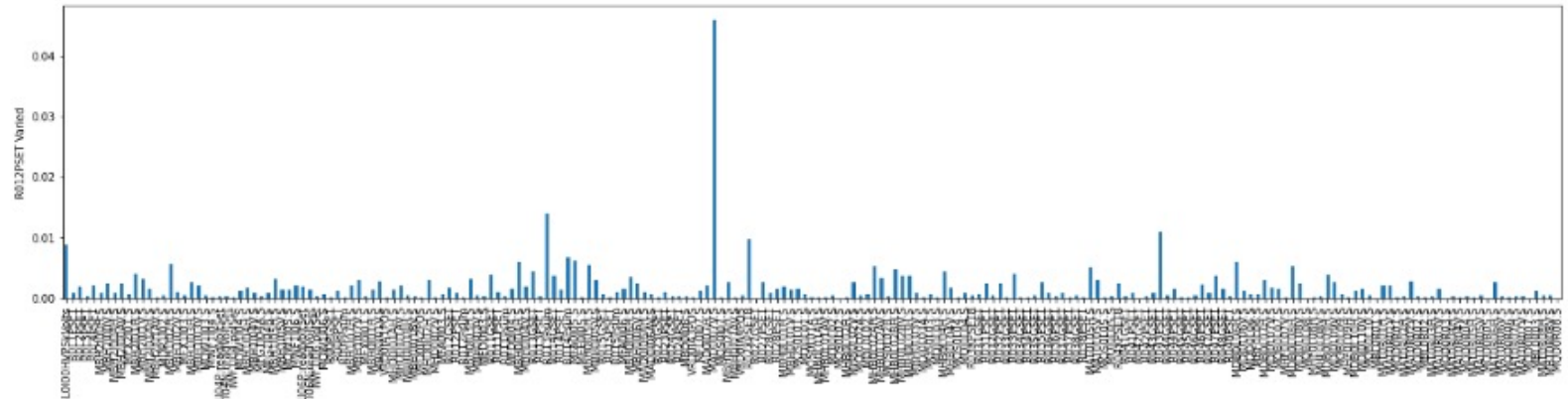
- Identifying individual errors using the inverse model

- Top: model error is a maximum for R014GSET which is the parameter that changed



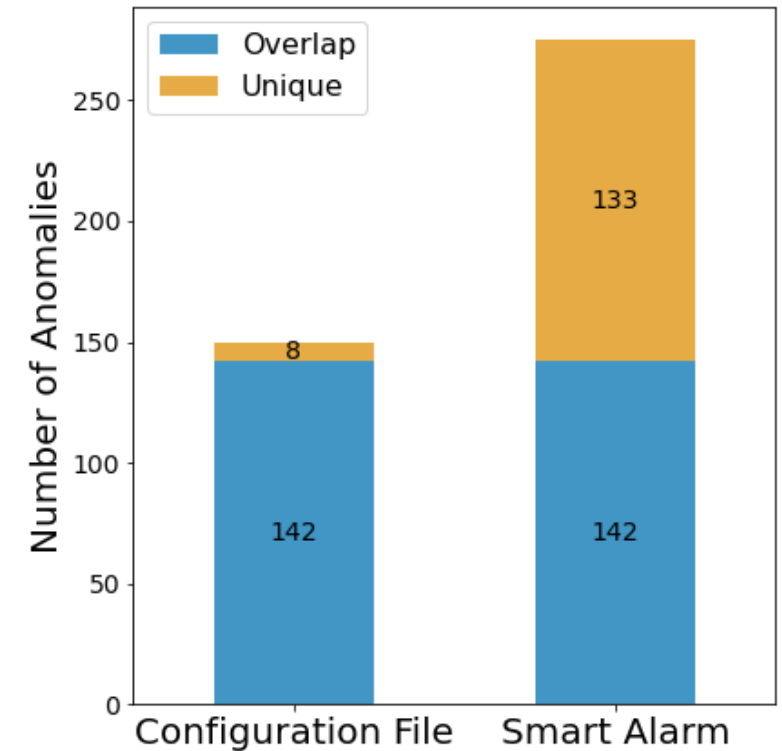
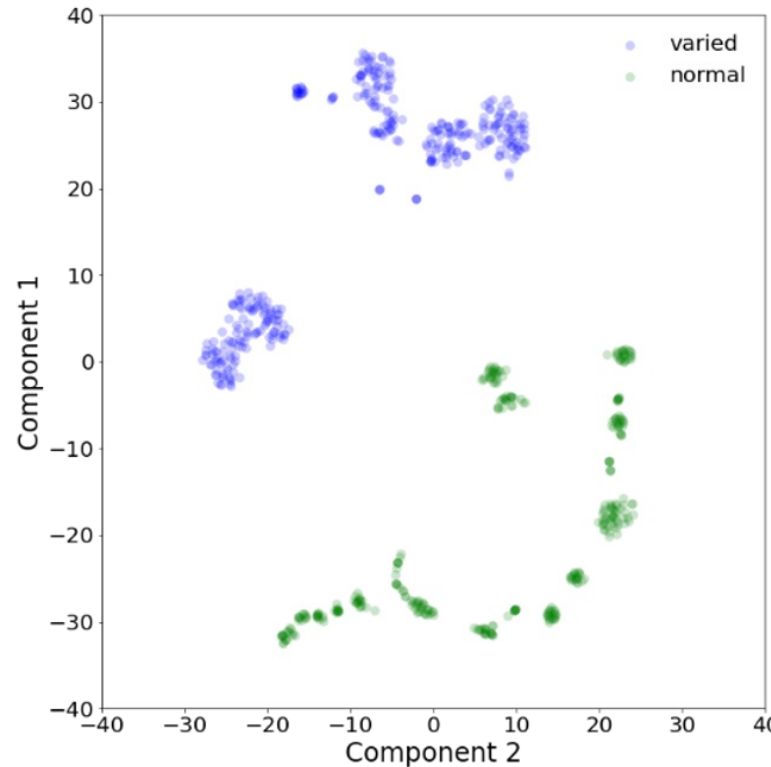
MAD0107V.BDL → 20.9

- Bottom: model error is maximum for MAD0107V which is the parameter that was changed



A Smart Alarm System for the CEBAF Injector

- Left: T-SNE was used to reduce the dataset dimensionality
 - Operational data is shown in green and the study data in blue
 - The model correctly flagged the study data as anomalous
 - The T-SNE reduction of the data also provides a strong indication that these two datasets are distinct in nature
- Right: Comparison with conventional threshold-based alarming.
 - Threshold misses numerous configurations that would be undesirable by the user program



Conclusions

- Smart alarm system at JLab
 - Algorithm development nearing completion, published (<https://iopscience.iop.org/article/10.1088/2632-2153/acb98d/meta>)
 - Many thanks to the efforts of Chris Tennant and the JLab team
- Beamline control algorithms at BNL
 - Algorithm development nearing completion, publication in preparation.

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